

Inductors in AC Circuits

$$\phi = LI$$

$$\frac{d\phi}{dt} = L \frac{dI}{dt} = V \xrightarrow[\text{Faraday's Law}]{\text{Laplace Transform}} L s I(s) = V(s) \quad \frac{V(s)}{I(s)} = sL$$

$s = j\omega$ Frequency Domain

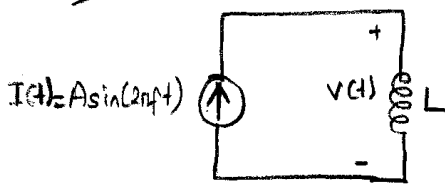
$$\frac{V(j\omega)}{I(j\omega)} = j\omega L = j 2\pi f L$$

$X_L = 2\pi f L$
↳ impedance of inductor.

* If f is increased $\left| \frac{V(j\omega)}{I(j\omega)} \right|$ increases assuming that $V(j\omega)$ is constant that will cause $|I(j\omega)|$ to decrease.

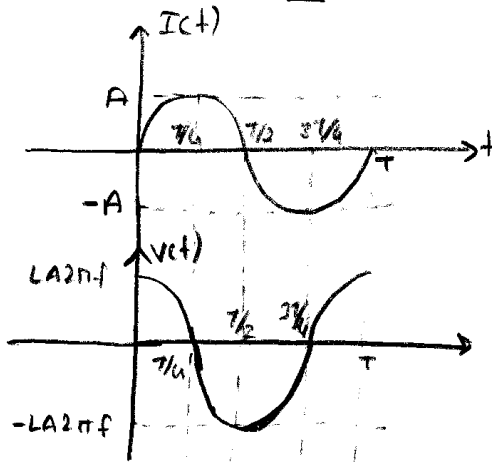
Hence, in AC excitation inductor behaves as open circuit.

Ex.



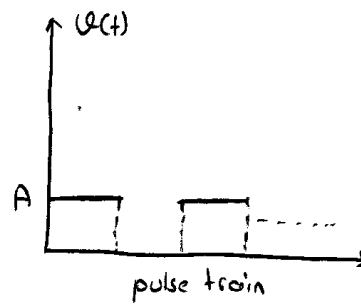
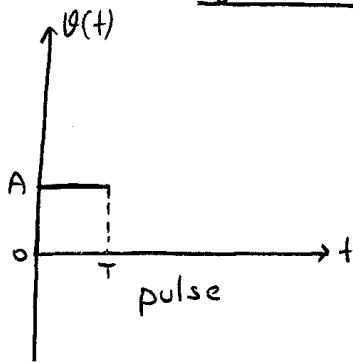
$$V(t) = L \frac{dI(t)}{dt} = L \frac{d}{dt} [A \sin(2\pi f t)]$$

$$V(t) = L A 2\pi f \cos(2\pi f t)$$

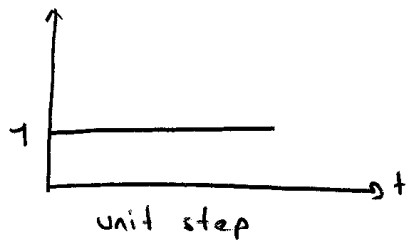


Current lags Voltage 90° for Inductors
↳ be behind

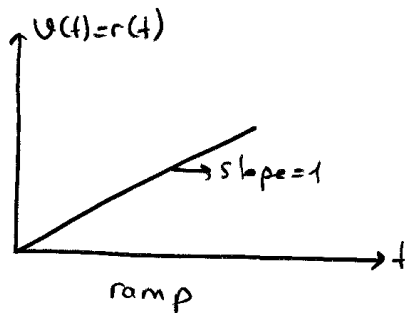
Typical Waveforms



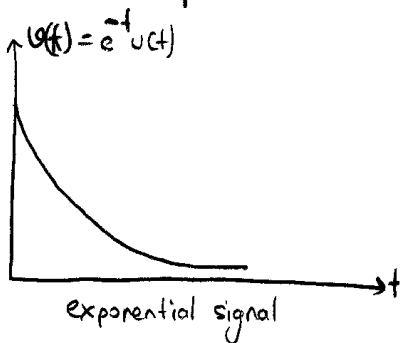
$$v(t) = u(t)$$

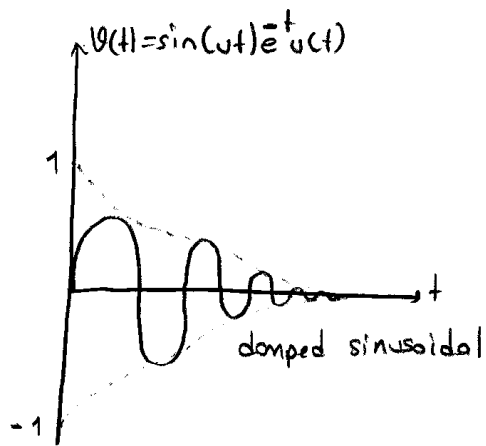


$$u(t) = \begin{cases} 1 & t > 0 \\ 0 & t < 0 \end{cases}$$

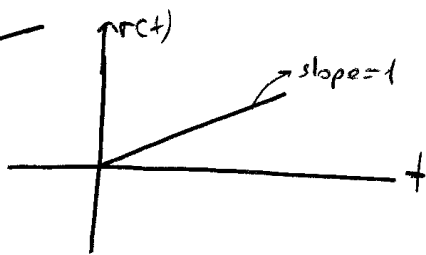


$$r(t) = \begin{cases} t & t \geq 0 \\ 0 & t < 0 \end{cases}$$

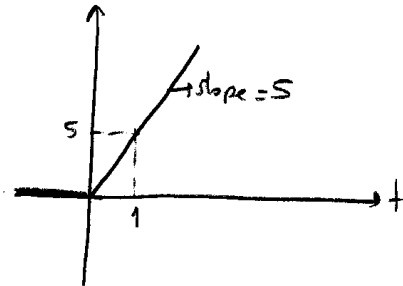




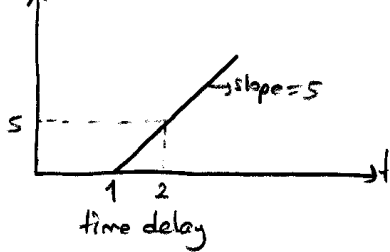
Ex.



$k(t) = Sr(t)$

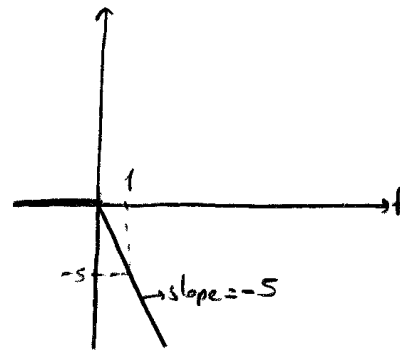


$k(t) = Sr(t-1)$

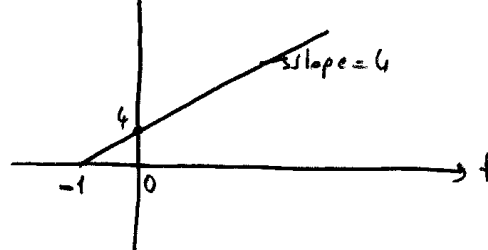


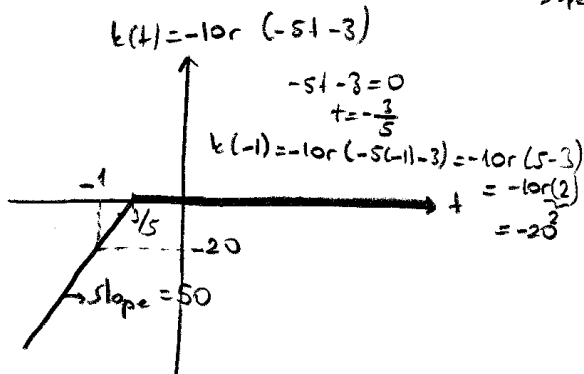
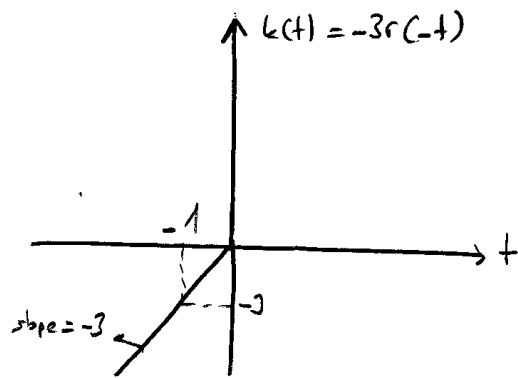
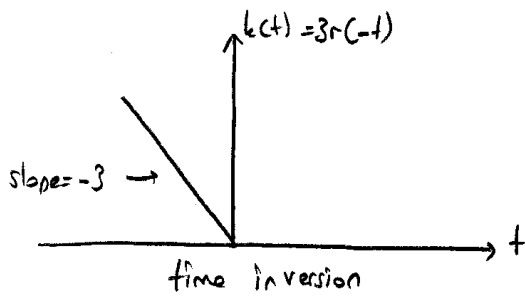
sketch $k(t) = Sr(t)$ $k(t) = -Sr(t)$
 $k(t) = Sr(t-1)$ $k(t) = 4r(t+1)$
 $k(t) = 3r(-t)$ $k(t) = -3r(-t)$
 $k(t) = 10r(-5t-3)$

$k(t) = -Sr(t)$



$k(t) = 4r(t+1)$

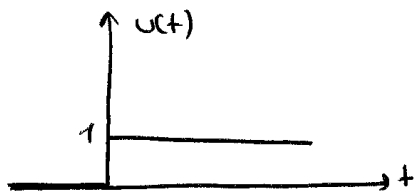




* $k(t) \rightarrow k(-t)$
 $|a| > 1$ compressing
 $|a| < 1$ extending

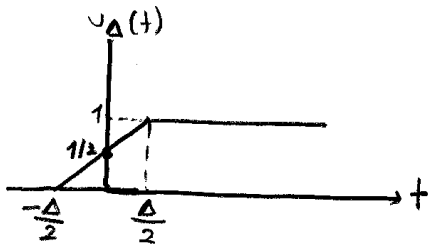
Unit-step function

$$u(t) = \begin{cases} 1 & t > 0 \\ 0 & t < 0 \end{cases}$$



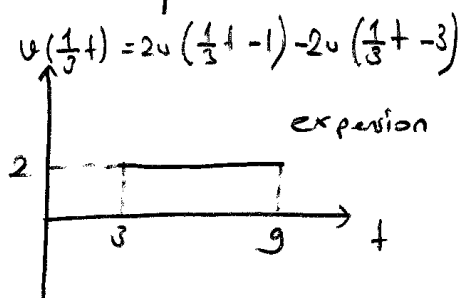
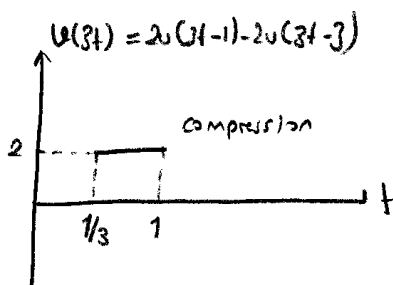
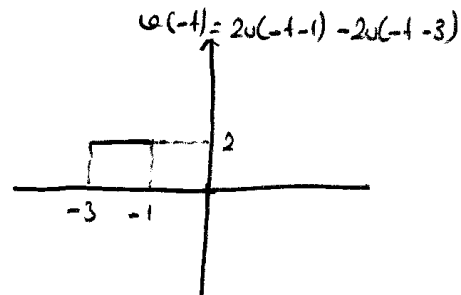
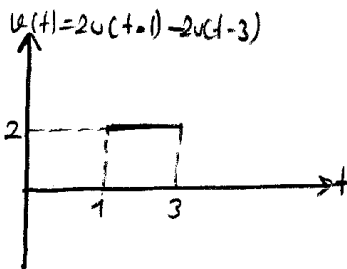
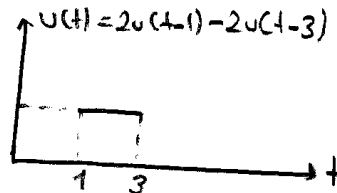
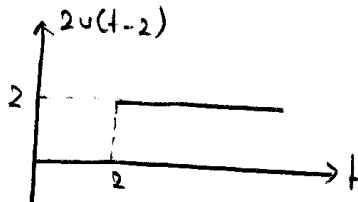
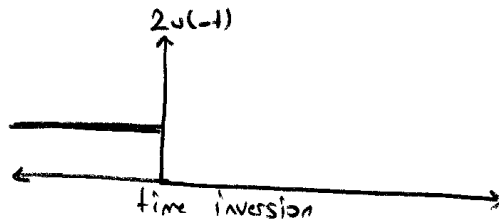
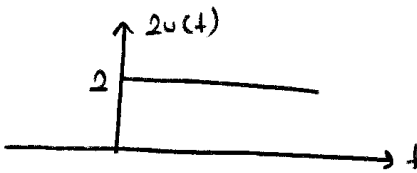
- * $u(t)$ has a jump discontinuity at $t=0$
- * $u(0)$ is generally undefined
- * If it is necessary to define a value for $u(t)$ when $t=0$ [$0 \leq u(0) \leq 1$]
 for example = $u(0) = \frac{1}{2}$

$$u(t) = \frac{dr(t)}{dt} \quad \text{function } r(t) = \int_{-\infty}^t u(t') dt' \rightarrow \text{indefinite integral} \quad \begin{cases} 0 & t < 0 \\ k & t > 0 \end{cases} \begin{matrix} k = \text{constant} \\ \int_{-\infty}^t u(t') dt' \\ \text{definite integral} \end{matrix}$$

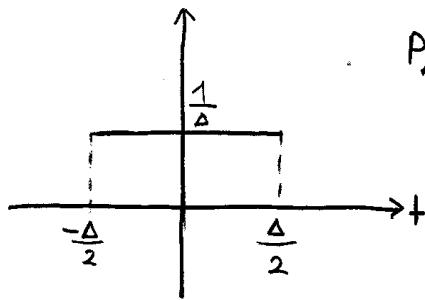


$$\text{let } u(t) = \lim_{\Delta \rightarrow 0} u_{\Delta}(t)$$

$$u_{\Delta}(0) = \frac{1}{2} \rightarrow u(0) = \frac{1}{2}$$



Pulse Function



$$P_{\Delta}(t) = \frac{d}{dt} u_{\Delta}(t)$$

$$P_{\Delta}(t) = \frac{u(t + \frac{\Delta}{2}) - u(t - \frac{\Delta}{2})}{\Delta}$$

$$P_{\Delta}(t) = P_{\Delta}(-t)$$

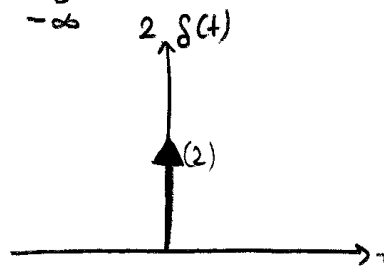
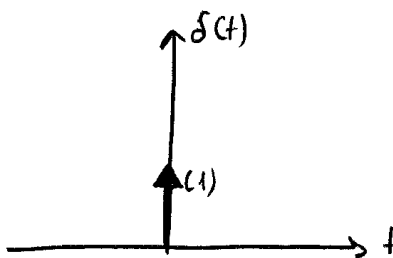
(even function)

$$\int_{-\infty}^{\infty} P_{\Delta}(t) dt = 1$$

Impulse Function

$$\delta(t) = \lim_{\Delta \rightarrow 0} P_{\Delta}(t) = \frac{d}{dt} u(t)$$

$$\delta(t) = \frac{d}{dt} u(t) \rightarrow u(t) = \int_{-\infty}^t \delta(t') dt'$$



$$* \delta(t) = \begin{cases} 0 & t \neq 0 \\ \text{singular} & t = 0 \end{cases}$$

$$* \delta(t) = \delta(-t) \text{ (Even function)}$$

$$* \int_{-\infty}^{\infty} \delta(t) dt = 1$$

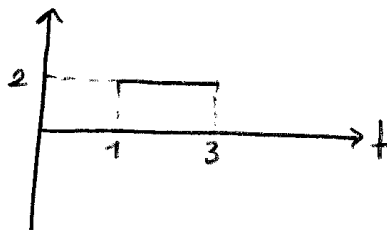
* If $f(t)$ is a continuous function at $t=0$, then $f(t) \cdot \delta(t) = f(0) \cdot \delta(t)$

$$\int_0^b \delta(t) dt = \begin{cases} a < 0, b < 0 & \text{then } 0 \\ a < 0, b > 0 & \text{then } 1 \\ a > 0, b > 0 & \text{then } 0 \\ a > 0, b < 0 & \text{then } -1 \end{cases}$$

$$* \int_{-\infty}^{\infty} f(t) \delta(t) dt = \int_{-\infty}^{\infty} f(0) \delta(t) dt = f(0) \underbrace{\int_{-\infty}^{\infty} \delta(t) dt}_{1} = f(0)$$

$$* \text{If } a \neq 0 \rightarrow \delta(at) = \frac{1}{|a|} \delta(t)$$

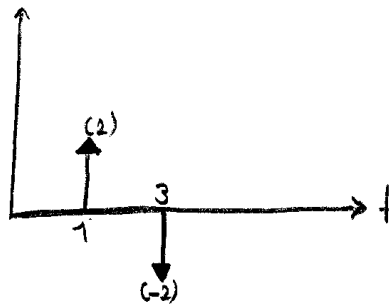
Ex. $v(t) = 2u(t-1) - 2u(t-3)$



Find $\frac{dv(t)}{dt} = ?$

Soln:

$$\frac{dv(t)}{dt} = 2\delta(t-1) - 2\delta(t-3)$$



Ex.

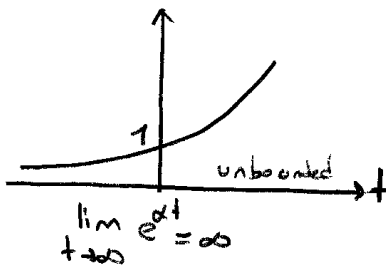
$f(t) = t$ - find $t \dot{f}(t)$

$$t \dot{f}(t) = t \left[\dot{f}(t) - \frac{d}{dt} t \right] + \int_{t=0}^t f(t)$$

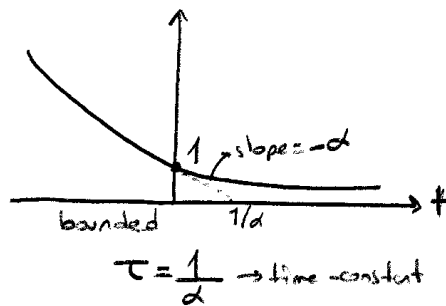
$$= 0 \dot{f}(t) - 1 f(t) = -f(t) \quad \boxed{t \dot{f}(t) = -f(t)}$$

Exponential Function

$f(t) = e^{\alpha t} \quad \alpha > 0$



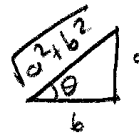
$f(t) = e^{-\alpha t} \quad \alpha > 0$



Sinusoidal Function

$\varphi(t) = a \sin(\omega t) + b \cos(\omega t)$

$\varphi(t) = \sqrt{a^2 + b^2} \cos\left(\omega t + \tan^{-1} \frac{a}{b}\right)$



$$\sin \theta = \frac{a}{\sqrt{a^2 + b^2}}$$

$$\cos \theta = \frac{b}{\sqrt{a^2 + b^2}}$$

$$\theta = \text{Arctan} \frac{a}{b}$$

$\varphi(t) = a \sin(\omega t) + b \cos(\omega t)$

$$= \sqrt{a^2 + b^2} \left[\frac{a}{\sqrt{a^2 + b^2}} \sin(\omega t) + \frac{b}{\sqrt{a^2 + b^2}} \cos(\omega t) \right]$$

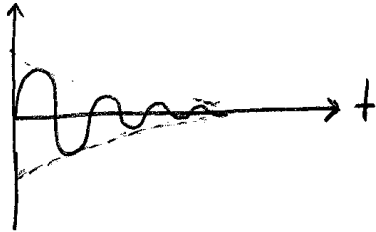
$$= \sqrt{a^2 + b^2} \left[\sin \theta \sin(\omega t) + \cos \theta \cos(\omega t) \right] = \sqrt{a^2 + b^2} \cos(\omega t - \theta)$$

$$= \sqrt{a^2 + b^2} \cos\left(\omega t - \tan^{-1} \frac{a}{b}\right)$$

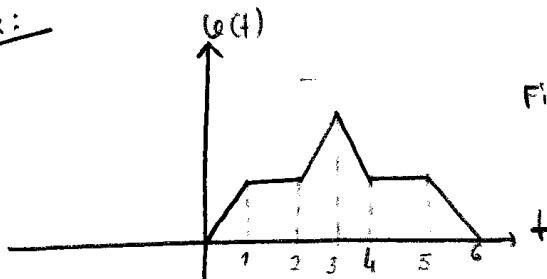
Composite Waveforms

$$f(t) = e^{-\frac{t}{\tau}} \sin(\omega t) u(t)$$

$$= e^{\underbrace{-\frac{t}{\tau}}_{\text{time constant}}} \sin\left(\underbrace{2\pi}_{\text{period}} t\right) u(t)$$



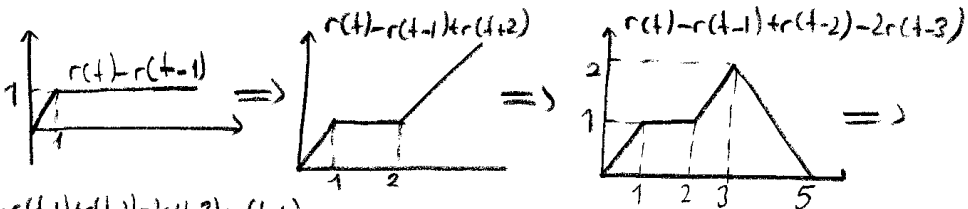
Ex:



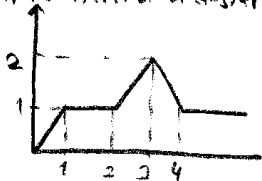
Find $q(t)$ in terms of $r(t)$, $u(t)$, $\delta(t)$

Soln:

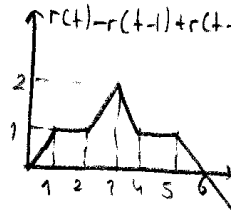
$$q(t) = r(t) - r(t-1) + r(t-2) - 2r(t-3) + r(t-4) - r(t-5) + r(t-6)$$



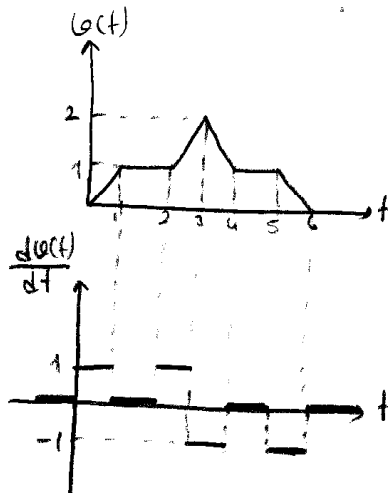
$$r(t) - r(t-1) + r(t-2) - 2r(t-3) + r(t-4)$$



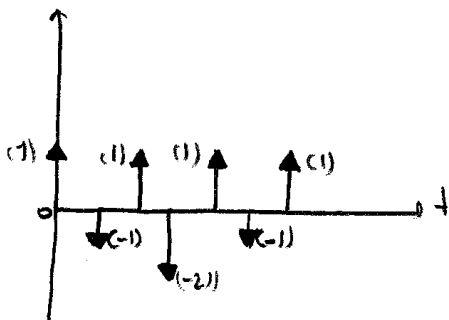
$$r(t) - r(t-1) + r(t-2) - 2r(t-3) + r(t-4) - r(t-5)$$



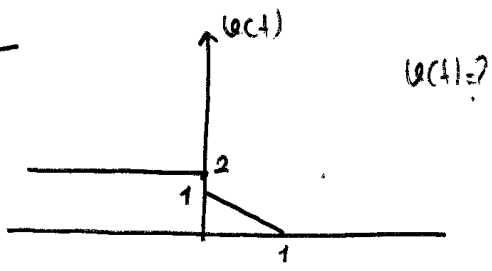
$$\begin{aligned} \frac{d(u(t))}{dt} &= u(t) - u(t-1) + u(t-2) - 2u(t-3) + u(t-4) - u(t-5) + u(t-6) \\ &= [u(t) - u(t-1)] + [u(t-2) - u(t-3)] - [u(t-3) - u(t-4)] - [u(t-5) - u(t-6)] \end{aligned}$$



$$\frac{d^2(u(t))}{dt^2} = \delta(t) - \delta(t-1) + \delta(t-2) - 2\delta(t-3) + \delta(t-4) - \delta(t-5) + \delta(t-6)$$



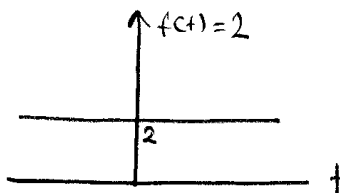
Ex.



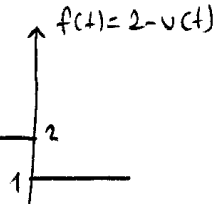
Soln.

$$f(t) = u(t)$$

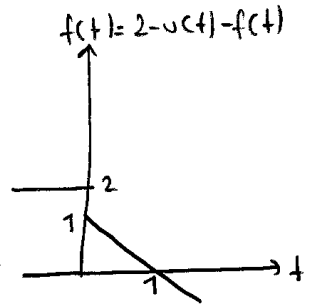
$$f(t) = 1$$



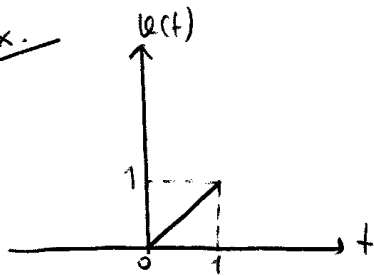
\Rightarrow



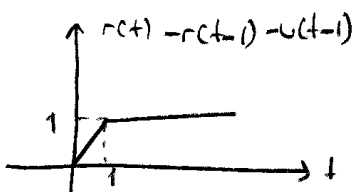
\Rightarrow



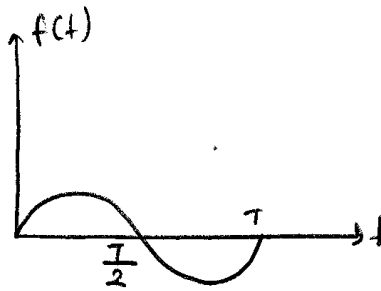
Ex.



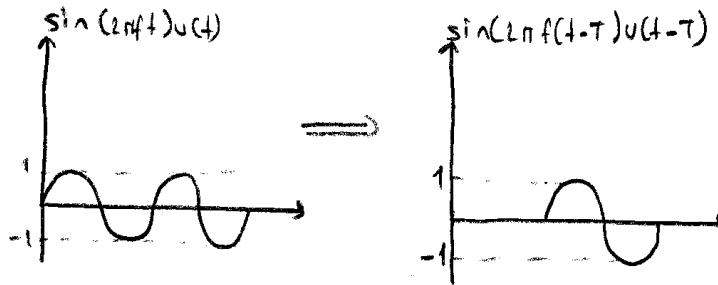
Soln.



Ex.



Soln:

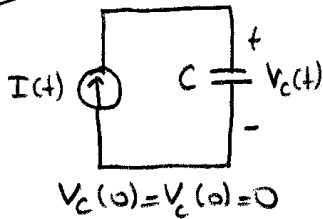


Continuity Property

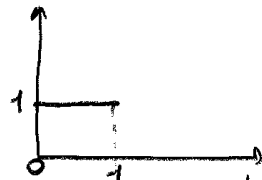
* Voltage across the capacitor is continuous if the current through the capacitor is bounded.

* Current through the inductor is continuous if the voltage across the inductor is bounded.

Ex.



a) $I(t) = u(t) - u(t-1)$



when $t < 1$ $I(t) = 1$ $t > 1$ $I(t) = 0$

$$V_c(t) = V_c(0) + \frac{1}{C} \int_0^t I(t') dt'$$

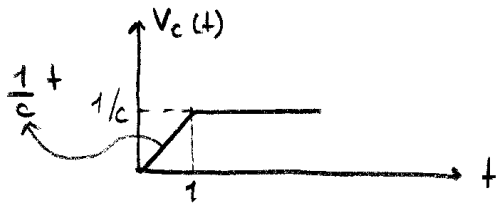
$$= 0 + \frac{1}{C} \int_0^t 1 dt' = 0 + \frac{1}{C} t \quad 0 < t < 1$$

When $t > 1$

$$V_c(t) = V_c(0) + \int_0^t I(t') dt'$$

$$= V_c(0) + \frac{1}{c} \cdot \int_0^1 1 dt + \underbrace{\int_1^t 0 dt}_0$$

$$= 0 + \frac{1}{c}$$



b) $I(t) = \delta(t)$ unbounded input when $t=0$

$0^- < t < 0^+$

$$V_c(t) = V_c(0) + \frac{1}{c} \int_{0^-}^t \delta(t') dt'$$

$$= 0 + \frac{1}{c} u(t) \quad V_c(0^+) = 0 + \frac{1}{c} = \frac{1}{c}$$

$t > 0$

$$V_c(t) = V_c(0^-) + \frac{1}{c} \int_{0^-}^t I(t') dt'$$

$$= 0 + \frac{1}{c} \left[\int_{0^-}^{0^+} \delta(t') dt' + \int_{0^+}^t 0 dt' \right]$$

$$= \frac{1}{c}$$

